Linguaggio L

Sintassi (BNF)

(by value)

C ::= nil | **Id** = **E** | **C**;**C** | if (**E**) {**C**} *[*else {**C**}*]* | while (**E**) {**C**} | **D**;**C** | return **E**
E ::= v | **Id** | **uop E** | **E bop E** | (**E**) | **Id**(**ae**)
D ::= nil | let **Id***[*:**T***]* = **E** | var **Id***[*:**T***]* = **E** | **D**;**D** | func **Id**(**form**) -> **T**`{C; return E}|form = ae|rec D`
form ::= nil | let **Id**:**T** , **form** | var **Id**:**T** , **form**
ae ::= nil | **E** , **ae**

uop ::= + | - | !
bop ::= + | - | * | \ | % | == | != | > | >= | < | <= | && | ||
Id ::= insieme degli identificatori validi
Val_E ::= $\mathbb{Z} \cup \mathbb{R} \cup$ {true, false} $\cup \{s \mid s \in ASCII^*\}$
T ::= Int | Double | Bool | String

`Int`	$n, n', n_1, ..$
`Double`	$d, d', d_1, ..$
`Bool`	$b, b', b_1, .. \in \{true, false\}$
`String`	$s, s', s_1, ..$

Metavariabili

$C, C', C'', C_0, C_1, ..$

$E, E', E'', E_0, E_1, ..$

$D, D', D'', D_0, D_1, ..$

$Id, Id', Id_1, x, x', x_1, ...$

$v, v', v'', v_0, v_1, ...$

$\tau, \tau', \tau'', \tau_0, \tau_1, ..$

(by reference)

`form ::= nil | let Id:T, form | var Id:T, form | ref Id:T, form`

`ae ::= nil | E , ae | l , ae`

Altri comandi:

C ::= do {**C**} while (**E**) | for (**D**; **E**; **C**) {**C**} | switch (**E**) {
case v1: **C**; break
case v2: **C**; break
:
*[*default: **C**; break*]*
}

C simbolo distinto della grammatica, quindi un **programma** è un comando

Semantica Statica

comando ben formato **C**: $\Delta \vdash_c C$

espressione ben formata **E**: $\Delta \vdash_e E : \tau$

dichiarazione ben formata **D**: $\Delta \vdash_e D : \Delta'$

ambiente statico Δ : Id $\cup$ Val $\longrightarrow T \cup T$Loc

Semantica Statica Espressioni

Assiomi: $(A1)\, \varnothing \vdash_e i : \text{Int}$, $(A2)\, \varnothing \vdash_e d : \text{Double}$, $(A3)\, \varnothing \vdash_e b : \text{Bool}$, $(A4)\, \varnothing \vdash_e s : \text{String}$

Regole di inferenza:

$$(R1)\ \frac{(\Delta(Id) = \tau \vee \Delta(Id) = \tau\text{Loc})}{\Delta \vdash_e Id : \tau},\quad (R2)\ \frac{\Delta \vdash_e E_1 : \tau_1, uop : \tau_1 \to \tau}{\Delta \vdash_e uop\, E_1 : \tau},\quad (R3)\ \frac{\Delta \vdash_e E_1 : \tau_1, \Delta \vdash_e E_2 : \tau_2, bop : \tau_1 \times \tau_2 \to \tau}{\Delta \vdash_e E_1\, bop\, E_2 : \tau}$$

$$(R4)\ \frac{\Delta \vdash_e E : \tau}{\Delta \vdash_e (E) : \tau}$$

Semantica Statica Comandi

Assiomi: $(A5)\, \varnothing \vdash_c nil$

Regole di inferenza:

$$(R5)\ \frac{\Delta(Id) = \tau\text{Loc}, \Delta \vdash_e E : \tau}{\Delta \vdash_c Id = E},\quad (R6)\ \frac{\Delta \vdash_c C_1, \Delta \vdash_c C_2}{\Delta \vdash_c C_1; C_2},\quad (R7)\ \frac{\Delta \vdash_e E : \text{Bool}, \Delta \vdash_c C_1, \Delta \vdash_c C_2}{\Delta \vdash_c \text{if } (E)\{C_1\} \text{ else } \{C_2\}}$$

$$(R8)\ \frac{\Delta \vdash_e E : \text{Bool}, \Delta \vdash_c C}{\Delta \vdash_c \text{while } (E)\ \{C\}},\quad (R9)\ \frac{\Delta \vdash_d D : \Delta', \Delta[\Delta'] \vdash_c C}{\Delta \vdash_c D; C}$$

$$\Delta[\Delta'](x) = \begin{cases} \Delta'(x), & \text{se } \Delta'(x) \text{ definito} \\ \Delta(x), & \text{altrimenti} \end{cases}$$

Semantica Statica Dichiarazioni

Assiomi: $(A6)\, \varnothing \vdash_d nil : \varnothing$

Regole di inferenza:

$$(R10)\ \frac{\Delta \vdash_e E : \tau, T == \tau}{\Delta \vdash_d \text{let } Id : T = E : [(Id, \tau)]},\quad (R11)\ \frac{\Delta \vdash_e E : \tau, T == \tau}{\Delta \vdash_d \text{var } Id : T = E : [(Id, \tau Loc)]},\quad (R12)\ \frac{\Delta \vdash_d D_1 : \Delta_1, \Delta[\Delta_1] \vdash_d D_2 : \Delta_2}{\Delta \vdash_d D_1; D_2 : \Delta_1[\Delta_2]}$$

Semantica Statica Funzioni

$$(FS1)\frac{\Delta \vdash_E E : \tau}{\Delta \vdash_C \text{return } E}$$

$$\begin{cases} \mathcal{T}(nil) = nil \\ \mathcal{T}(\text{let Id} : \tau, \text{form}) = \tau, \mathcal{T}(\text{form}) \\ \mathcal{T}(\text{var Id} : \tau, \text{form}) = \tau, \mathcal{T}(\text{form}) \end{cases}$$

$$(FS2)\frac{\text{form} : \Delta_0, \Delta[\Delta_0] \vdash_C C; \text{return } E, \Delta[\Delta_0] \vdash_E E : \tau}{\Delta \vdash_D \text{func Id(form)} \ \to \tau \ \{C; \text{return } E\} \ : \ [(\text{Id}, \mathcal{T}(\text{form}) \to \tau)]}$$

$$(FS3)\quad nil : \emptyset, \quad \frac{\text{form} : \Delta_0, \text{Id} \notin \Delta_0}{\text{let Id} : \tau, \text{form} : \Delta_0[(\text{Id}, \tau)]} \quad \frac{\text{form} : \Delta_0, \text{Id} \notin \Delta_0}{\text{var Id} : \tau, \text{form} : \Delta_0[(\text{Id}, \tau loc)]}$$

$$(FS4)\frac{\Delta \vdash_{ae} ae : aet, \Delta(\text{Id}) = aet \to \tau}{\Delta \vdash_E \text{Id}(ae) : \tau}$$

$$\begin{cases} \Delta \vdash_{ae} nil \\ \dfrac{\Delta \vdash_E E{:}\tau, \Delta \vdash_{ae} ae{:}aet}{\Delta \vdash_{ae} E, ae{:}\tau, aet} \end{cases}$$

(ricorsione)

$$(FS2') \vdash_D \text{func Id(form)} \ \to \tau \ \{C; \text{return } E\} \ : \ [(\text{Id}, \mathcal{T}(\text{form}) \to \tau)]$$

$$(FS2'')\frac{\text{form} : \Delta_0, \Delta[\Delta_0] \vdash_C C; \text{return } E, \Delta[\Delta_0] \vdash_E E : \tau}{\Delta \vdash_D \text{func Id(form)} \ \to \tau \ \{C; \text{return } E\}}$$

$$(RS1')\frac{\vdash_D D : \Delta}{\vdash_D rec\ D : \Delta}$$

$$(RS1'')\frac{\vdash_D D : \Delta', \Delta[\Delta'_{|I_0}] \vdash_D D}{\Delta \vdash_D rec\ D}, I_0 = FI(D) \cap BI(D)$$

Semantica Dinamica

esecuzione **C**: $\langle C,\rho,\sigma\rangle \longrightarrow_c \langle C',\rho',\sigma'\rangle$, $\mathbf{Exec}(C,\rho,\sigma) = \sigma' \iff \langle C,\rho,\sigma\rangle \longrightarrow_c^* \sigma'$

valutazione **E**: $\langle E,\rho,\sigma\rangle \longrightarrow_e \langle E',\rho,\sigma\rangle$, $\mathbf{Eval}(E,\rho,\sigma) = v \in Val \iff \langle E,\rho,\sigma\rangle \longrightarrow_e^* v$

elaborazione **D**: $\langle D,\rho,\sigma\rangle \longrightarrow_d \langle D',\rho',\sigma'\rangle$, $\mathbf{Elab}(D,\rho,\sigma) = \langle\rho',\sigma'\rangle \iff \langle D,\rho,\sigma\rangle \longrightarrow_d^* \langle\rho',\sigma'\rangle$

ambiente (dinamico) ρ : Id $\longrightarrow$ Loc ∪ Val memoria σ : Loc $\longrightarrow$ Val

$\longrightarrow_c$, $\longrightarrow_e$, $\longrightarrow_d$ sono le funzioni di interpretazione semantica di C, E e D

stato i

Istruzioni da eseguire
$\rho = \{(Id_0, L_0), \ldots, (Id_i, v_i), \ldots\}$
$\sigma = \{(L_0, v_0), \ldots, (L_i, v_i), \ldots\}$

$\longrightarrow_c$ $\longrightarrow_e$ $\longrightarrow_d$

stato i+1

Istruzioni da eseguire
$\rho' = \{(Id_0, L_0), \ldots, (Id_i, v_i), \ldots\}$
$\sigma' = \{(L_0, v_0'), \ldots, (L_i, v_i'), \ldots\}$

...

stato finale

nil
$\rho = \{(Id_0, L_0), \ldots, (Id_i, v_i), \ldots\}$
$\sigma = \{(L_0, v_0), \ldots, (L_i, v_i), \ldots\}$

Sistema di transioni

Semantica Dinamica Espressioni

$$(Id1)\ \frac{\rho(Id) = v \ \vee\ (\rho(Id) = L \in Loc \wedge \sigma(L) = v)}{\langle Id,\rho,\sigma\rangle \longrightarrow_e v}$$

$$(uop1)\ \frac{\langle E,\rho,\sigma\rangle \longrightarrow_e \langle E',\rho,\sigma\rangle}{\langle uop\,E,\rho,\sigma\rangle \longrightarrow_e \langle uop\,E',\rho,\sigma\rangle}$$

$$(uop2)\ \langle uop\ v,\rho,\sigma\rangle \longrightarrow_e v' = \text{uop}\ v$$

$$(bop1)\ \frac{\langle E_1,\rho,\sigma\rangle \longrightarrow_e \langle E_1',\rho,\sigma\rangle}{\langle E_1\,bop\,E_2,\rho,\sigma\rangle \longrightarrow_e \langle E_1'\,bop\,E_2,\rho,\sigma\rangle}$$

$$(bop2)\ \frac{\langle E_2,\rho,\sigma\rangle \longrightarrow_e \langle E_2',\rho,\sigma\rangle}{\langle v_1\,bop\,E_2,\rho,\sigma\rangle \longrightarrow_e \langle v_1\,bop\,E_2',\rho,\sigma\rangle}$$

$$(bop3)\ \langle v_1 bop\ v_2,\rho,\sigma\rangle \longrightarrow_e v = v_1\ \text{bop}\ v_2$$

!!! bop è sintassi
bop è semantica

Semantica Dinamica Comandi

$$(id2)\ \frac{\langle E,\rho,\sigma\rangle \longrightarrow_e^* v}{\langle Id = E,\rho,\sigma\rangle \longrightarrow_c \langle Id = v,\rho,\sigma\rangle} \qquad (id3)\ \langle Id = v,\rho,\sigma\rangle \longrightarrow_c \sigma[\rho(Id) = v]$$

$$(seq1)\ \frac{\langle C_1,\rho,\sigma\rangle \longrightarrow_c \langle C_1',\rho,\sigma'\rangle}{\langle C_1;C_2,\rho,\sigma\rangle \longrightarrow_c \langle C_1';C_2,\rho,\sigma'\rangle} \qquad (seq2)\ \frac{\langle C_1,\rho,\sigma\rangle \longrightarrow_c \sigma'}{\langle C_1;C_2,\rho,\sigma\rangle \longrightarrow_c \langle C_2,\rho,\sigma'\rangle}$$

$$(if1)\ \frac{\langle E,\rho,\sigma\rangle \longrightarrow_e^* true}{\langle \mathtt{if}\,(E)\{C_1\}\,\mathtt{else}\,\{C_2\},\rho,\sigma\rangle \longrightarrow_c \langle C_1,\rho,\sigma\rangle} \qquad (if2)\ \frac{\langle E,\rho,\sigma\rangle \longrightarrow_e^* false}{\langle \mathtt{if}\,(E)\{C_1\}\,\mathtt{else}\,\{C_2\},\rho,\sigma\rangle \longrightarrow_c \langle C_2,\rho,\sigma\rangle}$$

$$(rep1)\ \frac{\langle E,\rho,\sigma\rangle \longrightarrow_e^* true}{\langle \mathtt{while}\,(E)\{C\}\,\rho,\sigma\rangle \longrightarrow_c \langle C;\mathtt{while}\,(E)\{C\},\rho,\sigma\rangle} \qquad (rep2)\ \frac{\langle E,\rho,\sigma\rangle \longrightarrow_e^* false}{\langle \mathtt{while}\,(E)\{C\},\rho,\sigma\rangle \longrightarrow_c \sigma}$$

$$(b1)\ \frac{\langle D,\rho,\sigma\rangle \longrightarrow_d^* \langle \rho',\sigma'\rangle}{\langle D;C,\rho,\sigma\rangle \longrightarrow_c \langle C,\rho[\rho'],\sigma[\sigma']\rangle}$$

Semantica Dinamica Dichiarazioni

$$(let1)\ \frac{\langle E,\rho,\sigma\rangle \longrightarrow_e^* v}{\langle let\ Id : T = E,\rho,\sigma\rangle \longrightarrow_d \langle [(Id,v)],\sigma\rangle}$$

$$(var1)\ \frac{\langle E,\rho,\sigma\rangle \longrightarrow_e^* v}{\langle var\ Id : T = E,\rho,\sigma\rangle \longrightarrow_d \langle [(Id,new\,L)],[(L,v)]\rangle}$$

$$(dd1)\ \frac{\langle D_1,\rho,\sigma\rangle \longrightarrow_d \langle D_1',\rho',\sigma'\rangle}{\langle D_1;D_2,\rho,\sigma\rangle \longrightarrow_d \langle D_1';D_2,\rho',\sigma'\rangle} \qquad (dd2)\ \frac{\langle D_2,\rho[\rho_1],\sigma\rangle \longrightarrow_d \langle D_2',\rho[\rho_1]',\sigma'\rangle}{\langle \rho_1;D_2,\rho[\rho_1],\sigma\rangle \longrightarrow_d \langle \rho_1;D_2',\rho[\rho_1]',\sigma'\rangle}$$

$$(dd3)\ \langle \rho_1;\rho 2,\rho,\sigma\rangle \longrightarrow_d \langle \rho_1[\rho_2],\sigma\rangle$$

le regole (dd2) e (dd3) contengono configurazioni non ammissibili rispetto alla definizione di sistema di transizione

$(dd2)\ \langle \rho_1; D_2, \rho, \sigma \rangle, \langle \rho_1; D_2', \rho, \sigma' \rangle \quad (dd3)\ \langle \rho_1; \rho 2, \rho, \sigma \rangle$

la parte codice delle configurazioni di stato deve essere generabile dalla grammatiche che definisce D, e questo non vale per le configurazioni sopra

aggiungo gli ambienti alla sintassi

D ::= nil | let **Id**[:**T**] = **E** | var **Id**[:**T**] = **E** | **D**;**D** | ρ
T ::= Int | Double | Bool | String

!!! solo il compilatore può generare gli ambienti della sintassi, non l'utente

Il sistema di transizione delle dichiarazioni è

$(\{\langle D, \rho, \sigma \rangle \cup \langle \rho', sigma' \rangle\}, \longrightarrow_d, \{\langle \rho', sigma' \rangle\}, \langle$dichiarazione da elaborare, ambiente iniziale, memoria iniziale$\rangle)$

Semantica Dinamica Funzioni

$$(FD1)\frac{\langle \text{func Id(form)} \rightarrow T\{C; \text{return } E\}, \rho, \sigma \rangle}{\langle (Id, \lambda \text{ form}\,.\,\{\rho'; C; \text{return } E\}), \sigma \rangle} \qquad \begin{cases} \rho' = \rho_{|FV(C)-BV(form)} & \textit{scoping statico} \\ \rho' = nil & \textit{scoping dinamico} \end{cases}$$

$$(FD2)\frac{\rho(Id) = \lambda \text{ form}\,.\,C}{\langle Id(ae), \rho, \sigma \rangle \rightarrow_e \langle \{form = ae; C\}, \rho, \sigma \rangle}$$

$$(FD3)\frac{\langle E, \rho, \sigma \rangle \rightarrow_e \langle E', \rho, \sigma \rangle}{\langle E, ae, \rho, \sigma \rangle \rightarrow_{ae} \langle E', ae, \rho, \sigma \rangle} \qquad (FD4)\frac{\langle ae, \rho, \sigma \rangle \rightarrow_{ae} \langle ae', \rho, \sigma \rangle}{\langle k, ae, \rho, \sigma \rangle \rightarrow_{ae} \langle k, ae', \rho, \sigma \rangle}$$

$$(FD5)\frac{\langle ae, \rho, \sigma \rangle \rightarrow_{ae} \langle ae', \rho, \sigma \rangle}{\langle \text{form} = ae, \rho, \sigma \rangle \rightarrow_d \langle \text{form} = ae', \rho, \sigma \rangle} \qquad (FD6)\frac{ak \vdash \text{form} : \rho_0}{\langle \text{form} = ak, \rho, \sigma \rangle \rightarrow_d \langle \rho_0, \sigma \rangle}$$

$$nil \vdash nil : \emptyset \qquad \frac{ak \vdash \text{form} : \rho}{k, ak \vdash \text{let Id} : \tau, \text{form} : \rho[(\text{Id}, k)]} \qquad \frac{ak \vdash \text{form} : \rho}{k, ak \vdash \text{var Id} : \tau, \text{form} : \rho[(\text{Id}, l_{(new)})]}$$

$$(RD1)\frac{\langle D, \rho - I_0, \sigma \rangle \rightarrow_d \langle D', \rho', \sigma' \rangle}{\langle rec\ D, \rho, \sigma \rangle \rightarrow_d \langle rec\ D', \rho', \sigma' \rangle}, I_0 = FI(D) \cap BI(D)$$

$$(RD2)\ \langle rec\ \rho_0, \rho, \sigma \rangle \rightarrow \langle \{(f, \lambda form\,.\,(rec\ \rho_0) - form; C) \mid \rho_0(f) = \lambda form\,.\,C\}, \sigma \rangle$$

Scoping e Identificatori Liberi

$FI_e : E \rightarrow \{\text{occorrenze } Id \text{ liberi}\}$

$FI_e(\text{v}) = \varnothing$

$FI_e(\text{Id}) = \{\text{Id}\}$

$FI_e(\text{uop E}) = FI_e(\text{E})$

$FI_e(\text{E1 bop E2}) = FI_e(\text{E1}) \cup FI_e(\text{E2})$

$FI_c : C \rightarrow \{\text{occorrenze } Id \text{ liberi}\}$

$FI_c(\text{nil}) = \varnothing$

$FI_c(\text{Id = E}) = \{\text{Id}\} \cup FI_e(\text{E})$

$FI_c(\text{C1;C2}) = FI_c(\text{C1}) \cup FI_c(\text{C2})$

$FI_c(\text{if (E) \{C1\} else \{C2\}}) = FI_e(\text{E}) \cup FI_c(\text{C1}) \cup FI_c(\text{C2})$

$FI_c(\text{while (E) \{C\}}) = FI_e(\text{E}) \cup FI_c(\text{C})$

$FI_c(\text{D;C}) = FI_d(\text{D}) \cup (FI_c(\text{C}) - BI_d(\text{D}))$

$FI_d : D \rightarrow \{\text{occorrenze } Id \text{ liberi}\}$

$FI_d(\text{nil}) = \varnothing$

$FI_d(\text{let Id:T = E}) = FI_e(\text{E})$

$FI_d(\text{var Id:T = E}) = FI_e(\text{E})$

$FI_d(\text{D1;D2}) = FI_d(\text{D1}) \cup (FI_d(\text{D2}) - BI_d(\text{D1}))$

$BI_c = \overline{FI_c}$

$BI_e = \overline{FI_e}$

$BI_d = \overline{FI_d}$

$FI_c(\text{return E}) = FI_e(E)$

$FI_e(\text{Id(ae)}) = \{\text{Id}\} \cup FI_{ae}(ae)$

$FI_d(\text{func Id(form)->T\{C\}}) = FI_c(\text{C}) - BI_{form}(\text{form})$

$FI_{form}(\text{form}) = \varnothing$

$FI_{ae}(\text{E,ae}) = FI_e(E) \cup FI_{ae}(ae)$

Anatomia Funzioni